# First-principles Molecular Dynamics 

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## Motivation

Example: $3_{10 \text {-helix (Polyalanine) }}$


Vibrations at 298 K DFT-PBE MD run, 50 fs

DFT allows efficient first-principles calculation of the Born-Oppenheimer surface via Kohn-Sham formalism

By analysing the electronic structure,
the total energy and the bond lengths on the local minima of the BOS, many
important properties of the system Bart:be understood.
A microscopical system is never totally in rest in a local minimum. It's in motion.

## Motivation

Example: $3_{10}$-helix (Polyalanine)


Vibrations at 298 K DFT-PBE MD run, 50 fs

For many processes the dynamical properties of microscopic systems play an important role:
$\Rightarrow$ chemical reactions
$\Rightarrow$ diffusion
$\Rightarrow$ stability of molecule systems
Thermal equilibrium is determined by the minimum of the free energy, not by the minim $F=U-T S$ al energy
$\Rightarrow$ Are there methods to
describe $\quad$ the dynamical

## Motivation

Harmonic Approximation:
Complete statistical description of the system based on approximated dynamics
$H^{i o n} \approx \sum_{I=1}^{N^{i o n s}} \frac{1}{2 M_{I}} \frac{\partial^{2}}{\partial \mathbf{X}_{I}^{2}}+\frac{1}{2} \Delta \mathbf{X}^{t r} \underline{\underline{\mathbf{H}}} \Delta \mathbf{X} ; \quad \mathbf{X}=\left\{\mathbf{X}_{I}\right\} ; \quad H_{i j}=\left.\frac{\partial^{2} E^{\mathrm{BOS}}}{\partial \mathrm{X}_{\mathrm{i}} \partial \mathrm{X}_{\mathrm{j}}}\right|_{\mathbf{x}_{0}}$

Works well in describing the dynamics close to the local minima

Transition state theory can describe chemical reactions with high reaction barriers

$$
k_{b} T \ll \Delta E
$$

Breakdown of harmonic approximation:
$\Rightarrow$ chemical reactions with low barriers
$\Rightarrow$ complex systems with many local minima close to each other
$\Rightarrow$ For these systems the harmonic approximation has to be corrected!

## Motivation

Molecular Dynamics is a method to explore the phase space


## Outline

1. History of Molecular Dynamics
2. How does first-principles MD work ?

- integrating Newton's equation
- CPMD, Born-Oppenheimer Dynamics

3. What can one do with first-principles MD ?

- MD as method to explore the phase space
- statistical ensembles, temperature
- application area of first-principles MD

4. Tools to explore the Born-Oppenheimer surface implemented in SFHIngX

## History of Molecular Dynamics

1957 Interaction of hard spheres

$\Rightarrow \quad$ insight into the behaviour of simple liquids

Alder and Wainwright, JCP 27, 1208 (1957)

1964 Simulation of liquid argon
$\Rightarrow$ first simulation using a realistic empirical interaction potential

Rahman, PRA 136, 405 (1964)
Source: http://www.ch.embnet.org

## History of Molecular Dynamics

1974 Simulation of liquid water
$\Rightarrow$ first simulation of a realistic (bio)system

Stillinger and Rahman, JCP 60, 1545 (1974)

1977 Simulation of Bovine Pancreatic Trypsin Inhibitor
$\Rightarrow$ first simulation of a proteine
McCammon et al, Nature 267, 585 (1977)

Source: http: / /www.ch.embnet.org

## History of Molecular Dynamics

1985

R. Car and M. Parrinello, PRL 55, 2471 (1985)

## 1986

QUEST
$\Rightarrow$ QM/MM Dynamics ab-initio (QM) + force field (MM)

Kollmann and Singh

## What is first-principles MD?

Definition: (L1) First-principles Molecular Dynamics means classically treating the dynamics of the ion cores on the DFT (ground-state) Born-Oppenheimer potential surface

Realization: solving Kohn-Sham equations for given ionic positions

$$
\left\{\mathbf{X}_{I}\right\} \xrightarrow{K S} n_{g}\left(\left\{\mathbf{X}_{I}\right\}\right), E^{\mathrm{BOS}}\left(\left\{\mathbf{X}_{I}\right\}\right)
$$

calculating the forces acting on the ions via HF-Theorem

and solving the newtonian equations of motion

$$
\ddot{\mathbf{X}}_{I}=\frac{\mathbf{F}_{I}}{M_{I}}
$$

Approximations:Born-Oppenheimer Approximation (L2), XC-Functional (L8), classical treatment of ion cores

## MD-Loop of a DFT-Code



How are the ionic equations of motion integrated ?

## Integrating Newton's Equations


$\left\{\mathrm{X}_{I}\left(\mathrm{t}_{0}\right)\right\},\left\{\dot{\mathrm{X}}_{I}\left(\mathrm{t}_{0}\right)\right\} \xrightarrow{? ? ?}\left\{\mathrm{X}_{I}\left(\mathrm{t}_{1}\right)\right\},\left\{\dot{\mathrm{X}}_{I}\left(\mathrm{t}_{1}\right)\right\}$

Numerical integration schemes use finite time-steps to perform the integration!

$$
d t \quad \rightarrow \quad \Delta t
$$

A "good" integration scheme:
$\Rightarrow$ gives an accurate trajectory
$\Rightarrow$ conserves the total energy
$\Rightarrow$ uses as few time steps as possible

## Integrating Newton's Equations




Analytical Integration:

$$
\begin{aligned}
& \dot{\mathbf{X}}_{I}\left(t_{1}\right)=\dot{\mathbf{X}}_{I}\left(t_{0}\right)+\int_{t_{0}}^{t_{1}} d t \frac{\mathbf{F}_{I}[\mathbf{X}(t)]}{M_{I}} \\
& \mathbf{X}_{I}\left(t_{1}\right)=\mathbf{X}_{I}\left(t_{0}\right)+\int_{t_{0}}^{t_{1}} d t \dot{\mathbf{X}}_{I}(t)
\end{aligned}
$$

1 st order scheme
Simple example: Euler-scheme

$$
\begin{aligned}
& \mathbf{X}_{I}\left(t_{n+1}\right)=\mathbf{X}_{I}\left(t_{n}\right)+\Delta t \cdot \dot{\mathbf{X}}_{I}\left(t_{n}\right) \\
& \dot{\mathbf{X}}_{I}\left(t_{n+1}\right)=\dot{\mathbf{X}}_{I}\left(t_{n}\right)+\Delta t \cdot \ddot{\mathbf{X}}_{I}\left(t_{n}\right)
\end{aligned}
$$

$\Rightarrow$ only stable for very small time steps
$\Rightarrow$ alternative schemes ?

## Verlet Scheme

Taylor expansion for trajectory forward ...

$$
\left.\mathbf{X}_{I}\left(t_{n+1}\right)=\mathbf{X}_{I}\left(t_{n}\right)+\Delta t \cdot \dot{\mathbf{X}}_{I}\left(t_{n}\right)+\frac{\Delta t^{2}}{2!} \cdot \ddot{\mathbf{X}}_{I}\left(t_{n}\right)+\frac{\Delta t^{3}}{3!} \cdot \dddot{\mathbf{X}}_{I}\left(t_{n}\right)+\ldots+>\alpha^{4}\right)
$$

....and backward in time:

$$
\mathbf{X}_{I}\left(t_{n-1}\right)=\mathbf{X}_{I}\left(t_{n}\right)-\Delta t \cdot \dot{\mathbf{X}}_{I}\left(t_{n}\right)+\frac{\Delta t^{2}}{2!} \cdot \ddot{\mathbf{X}}_{I}\left(t_{n}\right)-\frac{\Delta t^{3}}{3!} \cdot \dddot{\mathbf{X}}_{I}\left(t_{n}\right)+\ldots+\not \partial\left(\dot{t}^{4}\right)
$$

time reversible 3rd order update scheme for particle positions:
$\longrightarrow \mathbf{X}_{I}\left(t_{n+1}\right)=2 \mathbf{X}_{I}\left(t_{n}\right)-\mathbf{X}_{I}\left(t_{n-1}\right)+\frac{\Delta t^{2}}{2!} \cdot \frac{\mathbf{F}_{I}\left(t_{n}\right)}{M_{I}} \leftarrow \mathbf{F}_{I}=M_{I} \ddot{\mathbf{X}}_{I}$

Big advantage: reversible in time !!

$$
\dot{\mathbf{X}}_{I}\left(t_{n}\right)=\frac{\mathbf{X}_{I}\left(t_{n+1}\right)-\mathbf{X}_{I}\left(t_{n-1}\right)}{2 \Delta t}
$$

Disadvantage:
actual velocities cannot b calculated directly
Connection of thermostat not straightforward

## Gear Predictor-Corrector

positions

velocities

accelerations

higher order
$\rightarrow$ time derivatives (up to $5^{\text {th }}$ order)

## 1. Predictor step

$$
\begin{aligned}
& \mathbf{X}_{I}^{p}\left(t_{n+1}\right)=\mathbf{X}_{I}^{p}\left(t_{n}\right)+\sum_{q=1}^{k} \frac{\Delta t^{q}}{q!}\left(\left.\frac{\partial^{q} \mathbf{X}_{I}^{p}}{\partial t^{q}}\right|_{t_{n}}\right) \\
& \mathbf{X}_{I}^{p}\left(t_{n+1}\right)=\dot{\mathbf{X}}_{I}^{p}\left(t_{n}\right)+\sum_{q=2}^{k} \frac{\Delta t^{q-1}}{(q-1)!}\left(\left.\frac{\partial^{q} \mathbf{X}_{I}^{p}}{\partial t^{q}}\right|_{t_{n}}\right. \\
& \vdots \\
& \left.\frac{\partial^{q} \mathbf{X}_{I}^{p}}{\partial t^{q}}\right|_{t_{n+1}}=\left.\frac{\partial^{q} \mathbf{X}_{I}^{p}}{\partial t^{q}}\right|_{t_{n}}
\end{aligned}
$$

2. Force calculation evaluation of predictor step
$\mathbf{F}_{I}\left(t_{n+1}\right)=\mathbf{F}_{I}\left(\left\{\mathbf{X}^{p}\left(t_{n+1}\right)\right\}\right)$

$$
\begin{aligned}
& \Delta \ddot{\mathbf{X}}_{I}=\frac{\mathbf{F}_{I}}{M_{I}}-\ddot{\mathbf{X}}_{I}^{p} \\
& \Delta \widetilde{\mathbf{X}}_{I}=\frac{1}{2} \Delta \ddot{\mathbf{X}}_{I}^{p} \cdot(\Delta t)^{2}
\end{aligned}
$$

3. Corrector step

$$
\begin{array}{lll}
\mathbf{X}_{I}\left(t_{n+1}\right) & =\mathbf{X}_{I}^{p}\left(t_{n+1}\right) & +\alpha_{0} \cdot \Delta \widetilde{\mathbf{X}}_{I} \\
\dot{\mathbf{X}}_{I}\left(t_{n+1}\right) \cdot \Delta t & =\dot{\mathbf{X}}_{I}^{p}\left(t_{n+1}\right) \cdot \Delta t+\alpha_{1} \cdot \Delta \widetilde{\mathbf{X}}_{I}
\end{array}
$$

$$
\frac{\left(\left.\frac{\partial^{k} \mathbf{X}_{I}}{\partial t^{k}}\right|_{t_{n+1}}\right) \cdot \Delta t^{k}}{k!}=\frac{\left(\left.\frac{\partial^{k} \mathbf{X}_{I}^{p}}{\partial t^{k}}\right|_{t_{n+1}}\right) \cdot \Delta t^{k}}{k!}+\alpha_{k} \cdot \Delta \widetilde{\mathbf{X}}_{I}
$$

## Gear Predictor-Corrector



Advantages: highly accurate particle positione( $\mathrm{t}^{5}$ ) accurate particle velocities $O\left(t^{4}\right)$ accurate particle accelerations $O\left(t^{3}\right)$

Direct calculation of the velocities makes connecting a thermostat straightforward

Disadvantage not reversible in time !

## Time Reversibility

Example : Vibrating dimer
Reversible Integrating scheme

closed phase space trajectory


Oscillation keeps total energy

Irreversible Integrating scheme

open phase space trajectory


## Comparison of integration schemes

3 3-helix (30 atoms)
$\mathrm{E}_{\text {ion }}^{\text {tot }} 0.08$ Hartree (@ 298K)


Small time steps:
$5^{\text {th }}$ order Predictor-Corrector more accurate than Verlet (3rd order scheme)

Large time steps:
Non reversible PC scheme shows a strong drift in the total energy; Time-reversible Verlet scheme much more stable

## Comparison of integration schemes

Example: Simulation of a Liquid


$$
v^{L J}(r)=\varepsilon\left(\frac{\sigma}{r^{12}}-\frac{\sigma}{r^{6}}\right)
$$

Gear Predictor Corrector more accurate for small time steps

But: Increase of error with increasing time step more drastic for PC-Gear
$\Rightarrow \quad$ Verlet more accurate for large time steps (!!!)

## MD-Loop of a DFT-Code



How is the electronic system updated in a MD run ?

## Born-Oppenheimer Dynamics



For each ionic step the electronic system is fully relaxed to the Born-Oppenheimer surface by an iterative minimization scheme !

The ionic movement is fully decoupled from the electronic relaxation.

Time step size must sample ionic movement
in all other respects parameter free

## Car-Parrinello MD

Car-Parrinello Lagrangian

$$
L^{C P}=\sum_{i} \mu_{i}\left\langle\dot{\psi}_{i} \mid \dot{\psi}_{i}\right\rangle+\frac{1}{2} \sum_{I} M_{I} \dot{\mathbf{X}}_{I}^{2}-\widetilde{E}^{\mathrm{BOS}}[\Psi, \mathbf{X}]
$$



Small artificial electron masses m

$2^{\text {nd }}$ order equation of motion for the ions

Newtonian equations of motion on the BO surface
$2^{\text {nd }}$ order equation of motion for the electrons


Oscillations around ground-state for given ionic positions

## Car-Parinello MD



Electronic wavefunctions and ionic positions are updated simultaneously

Electronic system performs oscillations around ground-state for given ionic positions

Electronic oscillations must be significantly faster then ionic oscillations (frequency controlled by artificial electronic masses)

Time step size must sample electronic movement

## Comparison

## Example: Simulation of water [1]



Time step of a Born-Oppenheimer MD is $\mathfrak{a} 10 x$ larger than that of a CPMD』

But: Born-Oppenheimer MD needs to fully relax the electronic groundstate

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SFHIngX: Allstate-CCG + first order wavefunction extrapolation
$\Rightarrow 4-5$ electronic steps per ionic step (for timestep of 1 f
$\Rightarrow 1$ Alstate-CCG step needs twice the time then a $2^{\text {nd }}$ order electronic minimizer
$\Rightarrow$ CPMD and SFHIngX Born-Oppenheimer MD show comparable efficiency :
[1] Y. Laudernet, Using CPMD in order to improve classical simulations, CINECA Report (2001)

## Comparison

## Example: Simulation of Metals

## Car-Parrinello MD:

lowest oscillation frequency in the electronic system is given by energy gap

$\Rightarrow \quad$ electronic system cannot be decoupled from ionic system in metals
$\Rightarrow$ correcting thermostat necessary, simulation not straightforward

## Born-Oppenheimer MD:

simulation as straightforward as for insulators
(Performance comparison not yet done)

## Exploring the phase space with MD

 What can one do with a MD-run?

## Statistical Ensembles

MD-trajectory yields ensemble of possible microscopic states of the system

## MD-Trajectory $\stackrel{\text { Ergodicity Hypothesis }}{\longleftrightarrow}$ Statistical Ensemble

Ensemble averages can be identified with macroscopic observables

Example:


MD connects microscopic DFT-calculation with macroscopic observables

## Statistical Ensembles


$\Rightarrow$ How is temperature enabled ?

## Nosé-Hoover Thermostat

Additional degree of freedom (friction 区) simulates energy exchange with heat bath:

$$
\ddot{\mathbf{X}}_{I}=\frac{\mathbf{F}_{I}}{M_{I}} \quad \Rightarrow \quad \begin{aligned}
& \ddot{\mathbf{X}}_{I}=\frac{\mathbf{F}_{I}}{M_{I}}-\xi \cdot \mathbf{P}_{I} \\
& \dot{\xi}=\frac{1}{Q}\left(E^{\mathrm{kin}}\left(\left\{\dot{\mathbf{X}}_{I}\right\}\right)-L \cdot k_{B} T\right)
\end{aligned}
$$

L: degrees of freedom Q: thermostat mass
T: temperature


$$
H^{\mathrm{NH}}=E^{\mathrm{tot}}+\frac{1}{2} Q \xi^{2}+\xi \frac{L}{k_{B} T}
$$

$\Rightarrow \quad$ Nose-Hoover thermostat exactly simulates canonical ensemble!

## The role of the thermostat mass Q

Example: Simulation of Methane at 298K


Simulation time o ( $\mathbf{0 . 4} \mathbf{~ p s}$ )
large Q's
Total energy oscillates with characteristic frequency
$\omega \propto 1 / \sqrt{Q}$
small Q's
Characteristic frequency couples to vibrations of the system
$\Rightarrow$ small Q lead to faster generation of the wanted temperature but: too small Q lead to instabilities in the integration process

## Summary

What can one do with (first-principles) Molecular Dynamics ?


## Application-area of DFT-MD

Maximal system size (L1) order of 100 atoms
Maximal simulation time (L1) order of 100 ps , 10000 hydrogen-stretch vibrations
$\Rightarrow \quad$ no simulation of "rare" events possible (Transition state theory, physical intiution)
$\Rightarrow \quad$ good for analysing microscopic processes which take place on time scale of 1 ps ( 100 hydrogen-stretch vibrations)
embedding of the system in a realistic environment (e.g. water ) possible via QM/MM

## Exploring the BOS with SFHIngX

## Structure optimization


implemented schemes
Damped Newton (Verlet) Quasi Newton scheme

## Exploring the BOS with SFHIngX

## Transition State Search



## implemented scheme:

Initialization: synchronous transit
Optimization: quasi newton (gradient minimizer)

## Exploring the BOS with SFHIngX Vibrational analysis

Example: Phonon dispersion relation of the polyalanine a -helix calculated with DFT-PBE [1] and compared to experimental values of [2]





## implemented schemes

Frozen Phonon vibrational analysis Harmonic thermodynamic analysis (sxgetdyn)
Phonon dispersion relation (sxdispersion, not documented in manual)
[1] L. Ismer, J. Ireta, S. Boeck and J. Neugebauer, to be published
[2] H. Lee and S. Krimm, Biopolymers 46, 283 (1998)

## Exploring the BOS with SFHIngX

## Molecular Dynamics



